

Radiosity

Classic radiosity = finite element method

Assumptions

- Diffuse reflectance
- Usually polygonal surfaces

Advantages

- View independent solution

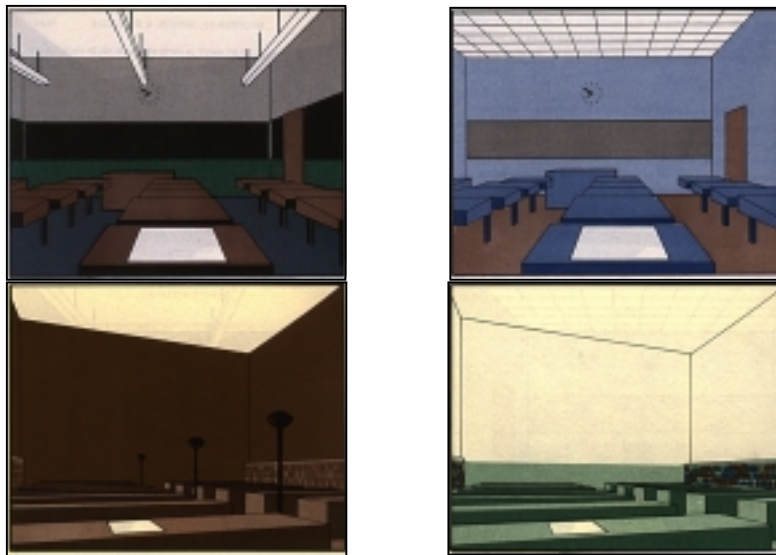
Techniques

- Meshing
- Form factors
- Solving linear equations

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First Radiosity Pictures ...



Parry Moon and Domina Spencer (MIT), *Lighting Design*, 1948

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Early Radiosity



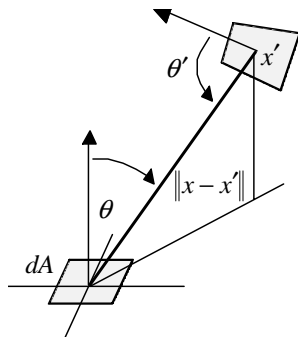
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The Radiosity Equation


Assume diffuse reflection only

Solve for radiosity (2D function)



$$B(x) = B_e(x) + \rho(x)E(x)$$

$$B(x) = B_e(x) + \rho(x) \int F(x, x') B(x') dA'$$

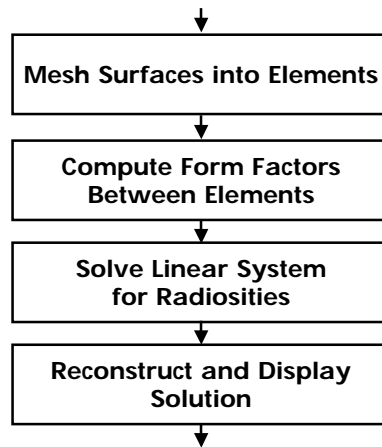
M^2 

$$F(x, x') = \frac{G(x, x')}{\pi} = \frac{\cos \theta \cos \theta'}{\pi \|x - x'\|^2} V(x, x')$$

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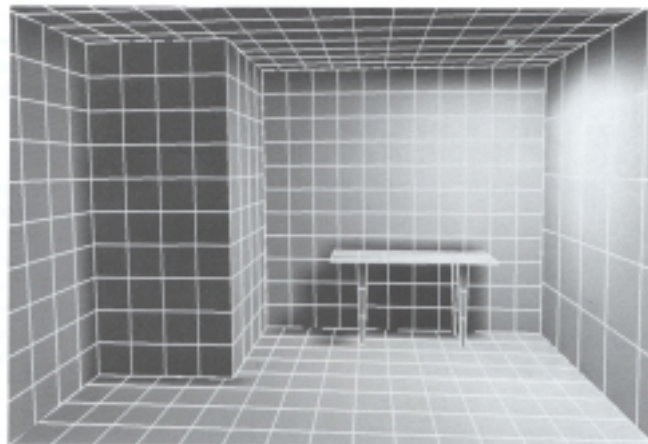
Classic Radiosity Algorithm



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Simple Room Scene



Example from John Wallace

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Derivation

Radiosity integral equation

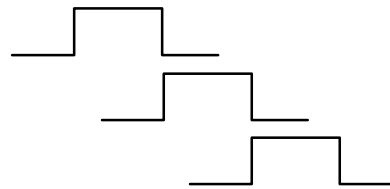
$$B(x) = B_e(x) + \rho(x) \int_{M^2} B(x') F(x, x') dA'$$

Piecewise constant basis functions

$$B(x) = \sum_i B_i N_i(x)$$

$$B_e(x) = \sum_i E_i N_i(x)$$

$$\rho(x) = \sum_i \rho_i N_i(x)$$



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Derivation

Convert integral equation to matrix equation

$$B(x) = B_e(x) + \rho(x) \int_{M^2} F(x, x') \sum_j B_j N_j(x') dA'$$

$$\sum_i B_i N_i(x) = \sum_i B_i N_i(x) + \sum_i \rho_i N_i(x) \left[\sum_j B_j \int_{M^2} F(x, x') N_j(x') dA' \right]$$

$$\int \left(\sum_i B_i N_i(x) = \sum_i B_i N_i(x) + \sum_i \rho_i N_i(x) \left[\sum_j B_j \int_{M^2} F(x, x') N_j(x') dA' \right] \right) dA$$

$$B_i A_i = E_i A_i + \rho_i \sum_j B_j \int_{M^2} \int_{M^2} F(x, x') N_i(x) N_j(x') dA dA'$$

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Form Factor

Throughput

$$T_{ij} = T_{ji} = \int_{A_i} \int_{A_j} \frac{\cos \theta'_o \cos \theta_i}{\pi \|x - x'\|^2} V(x, x') dA dA'$$

Reciprocity

$$\begin{aligned} T_{ij} &\equiv A_i F_{ij} \\ T_{ji} &\equiv A_j F_{ji} \end{aligned} \Rightarrow A_i F_{ij} = A_j F_{ji}$$

Summation

$$\sum_j F_{ij} = \sum_i F_{ji} = 1$$

Form factor is the percentage of light ...

Classic Radiosity

Power Balance

$$B_i A_i = E_i A_i + \rho_i \sum_j B_j A_j F_{ji}$$

Reciprocity

$$A_i F_{ij} = A_j F_{ji} \Rightarrow B_i = E_i + \rho_i \sum_j F_{ij} B_j$$

Radiosity System

$$\begin{pmatrix} 1 - \rho_1 F_{11} & -\rho_1 F_{12} & \cdots & -\rho_1 F_{1n} \\ -\rho_2 F_{21} & 1 - \rho_2 F_{22} & \cdots & -\rho_2 F_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ -\rho_n F_{n1} & -\rho_n F_{n2} & \cdots & 1 - \rho_n F_{nn} \end{pmatrix} \begin{pmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{pmatrix} = \begin{pmatrix} E_1 \\ E_2 \\ \vdots \\ E_n \end{pmatrix}$$

Form Factors

Differential-differential - $F(x, x') dA'$

$$F_{dA_i, dA_j} = \frac{\cos \theta'_o \cos \theta_i}{\pi \|x - x'\|^2} V(x, x') dA'$$

Differential-finite - $E_j(x)$

$$F_{dA_i, A_j} = \int_{A_j} \frac{\cos \theta'_o \cos \theta_i}{\pi \|x - x'\|^2} V(x, x') dA'$$

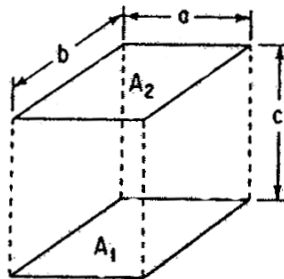
Finite-finite - $\Phi_{i,j}$

$$F_{A_i, A_j} = \frac{1}{A_i} \int_{A_i} \int_{A_j} \frac{\cos \theta'_o \cos \theta_i}{\pi \|x - x'\|^2} V(x, x') dA dA'$$

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Analytical Form Factors



$$X = \frac{a}{c}$$

$$Y = \frac{b}{c}$$

$$F_{A_1, A_2} = \frac{2}{\pi XY} \left\{ \ln \left[\frac{(1 + X^2)(1 + Y^2)}{(1 + X^2 + Y^2)} \right]^{\frac{1}{2}} + X \sqrt{1 + Y^2} \tan^{-1} \frac{X}{\sqrt{1 + Y^2}} \right. \\ \left. + Y \sqrt{1 + X^2} \tan^{-1} \frac{Y}{\sqrt{1 + X^2}} - X \tan^{-1} X - Y \tan^{-1} Y \right\}$$

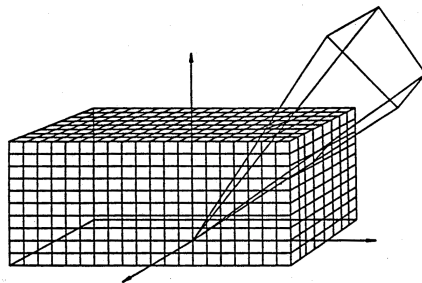
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Hemicube Algorithm

First radiosity algorithm to deal with occlusion

1. Render scene from the point of view of each vertex/element
2. Compute delta form factors - contribution from each pixel



Typical resolution: 32x32

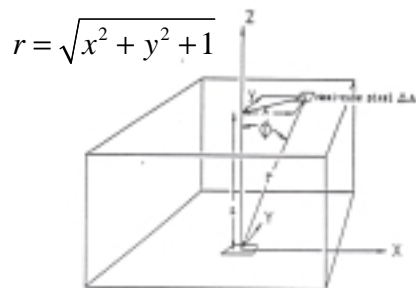
Render source elements from
POV of receiving element

$$F_{dA_i, A_j} = \sum_{p \in A_j} \Delta F_p$$

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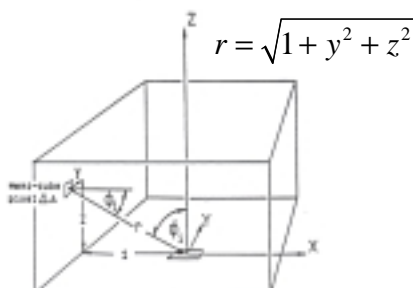
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Hemicube Delta Form Factors



$$\cos \phi = \frac{1}{\sqrt{x^2 + y^2 + 1}}$$

$$\Delta F = \frac{\Delta A}{\pi(x^2 + y^2 + 1)^2}$$



$$\cos \phi = \frac{1}{\sqrt{1 + y^2 + z^2}}$$

$$\Delta F = \frac{\Delta A}{\pi(1 + y^2 + z^2)^2}$$

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Hemicube Algorithms

Advantages

- + First practical method -> Patent!
- + Use existing rendering systems; Hardware!
- + Computes all form factors in $O(n)$

Disadvantages

- Computes differential-finite form factor
- Aliasing errors due to sampling
Randomly rotate/shear hemicube
- Proximity errors
- Visibility errors
- Expensive to compute a single form factor

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Solve $[F][B] = [E]$

Direct methods: $O(n^3)$

- Gaussian elimination

Goral, Torrance, Greenberg, Battaile, 1984

Iterative methods: $O(n^2)$

Convergence

Energy conservation -> diagonally dominant -> converge

- Gauss-Seidel, Jacobi: Gathering

Nishita, Nakamae, 1985

Cohen, Greenberg, 1985

- Southwell: Shooting

Cohen, Chen, Wallace, Greenberg, 1988

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Iterative Solvers

Iteration

$$(I - F)^{-1} B = E$$

$$B = (I + B + B^2 + \dots)E$$

$$B^0 = E$$

$$B^1 = E + FB^0$$

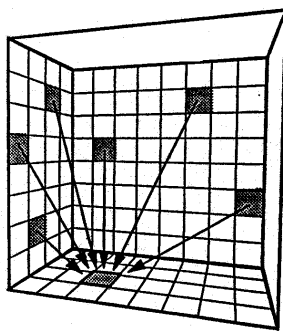
...

$$B^n = E + FB^{n-1}$$

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Gathering



```
for(i=0; i<n; i++)  
    B[i] = Be[i];  
  
while( !converged ) {  
    for(i=0; i<n; i++) {  
        E[i] = 0;  
        for(j=0; j<n; j++)  
            E[i] += F[i][j] * B[j];  
        B[i] = rho[i]*E[i];  
    }  
}
```

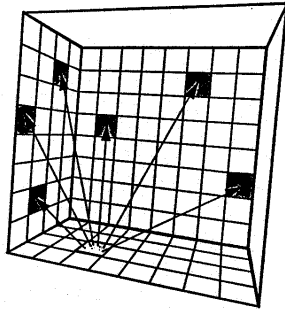
Row of F times B

Calculate one row of F and discard

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Shooting

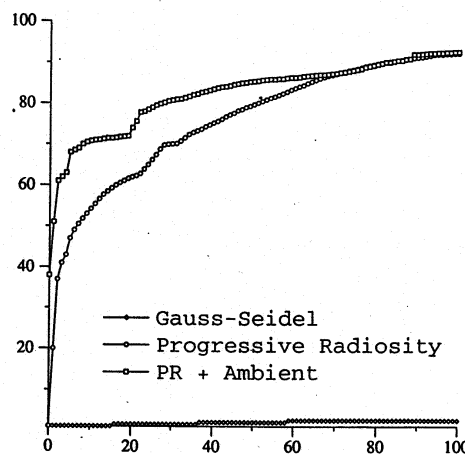


Brightness order

Column of F times B

```
for(i=0; i<n; i++)
  B[i] = dB[i] = Be[i];
while( !converged ) {
  set i st dB[i] is the largest;
  for(j=0; j<n; j++)
    if(i!=j) {
      dBj = rho[j]*F[j][i]*dB[i];
      dB[j] += dBj;
      B[j] += dBj;
    }
  dB[i]=0;
}
```

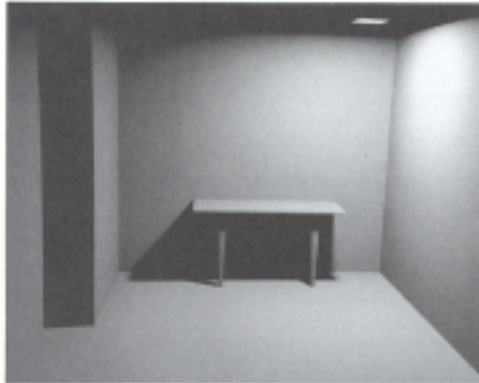
Results: Gathering vs. Shooting



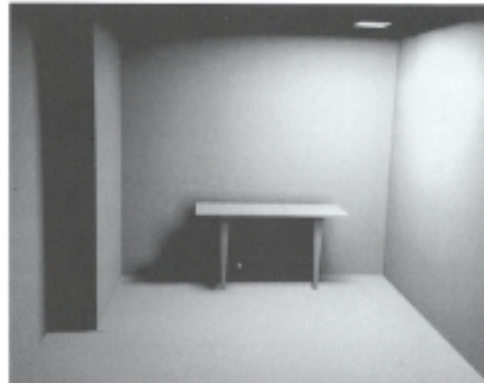
From Cohen et al.

Figure 5.9: Convergence versus number of steps for three algorithms.

Accuracy



Reference Solution



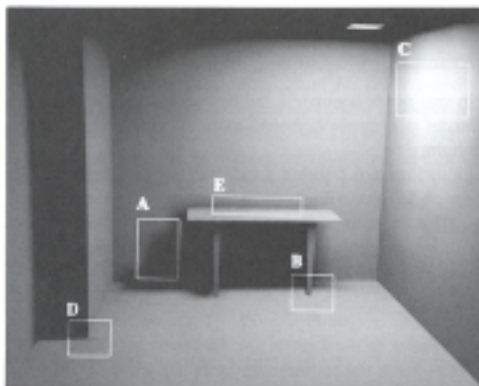
Uniform Mesh

Table in room sequence from Cohen and Wallace

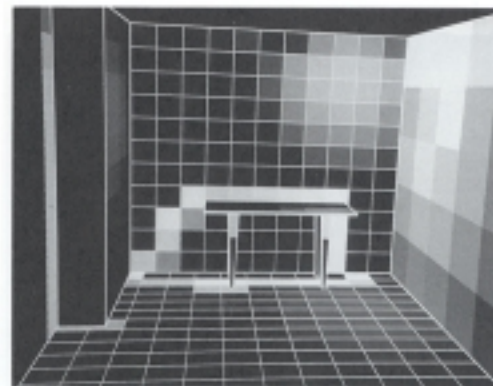
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Artifacts



- A. Blocky shadows
- B. Missing features
- C. Mach bands
- D. Inappropriate shading discontinuities
- E. Unresolved discontinuities

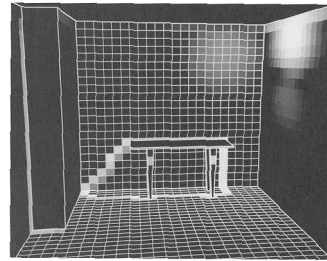
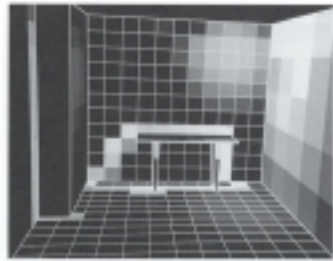
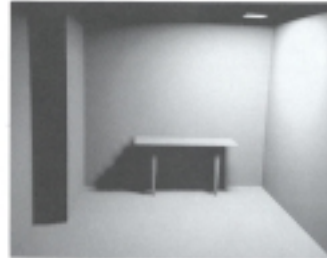
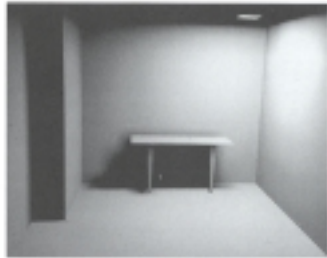


Error Image

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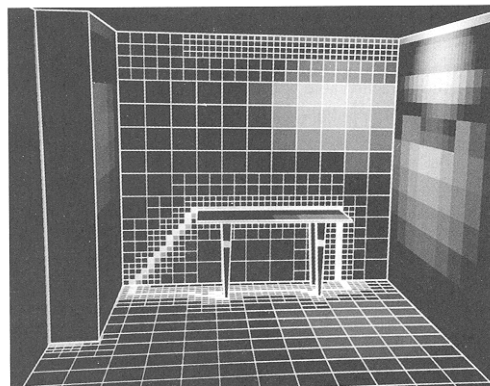
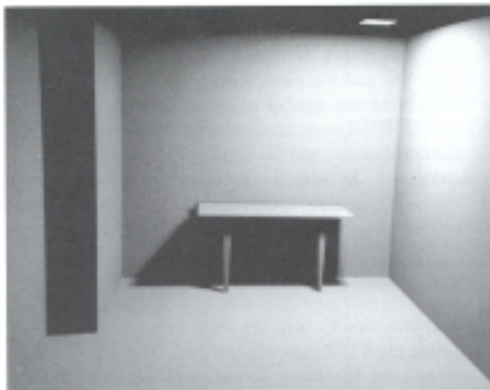
Increasing Resolution



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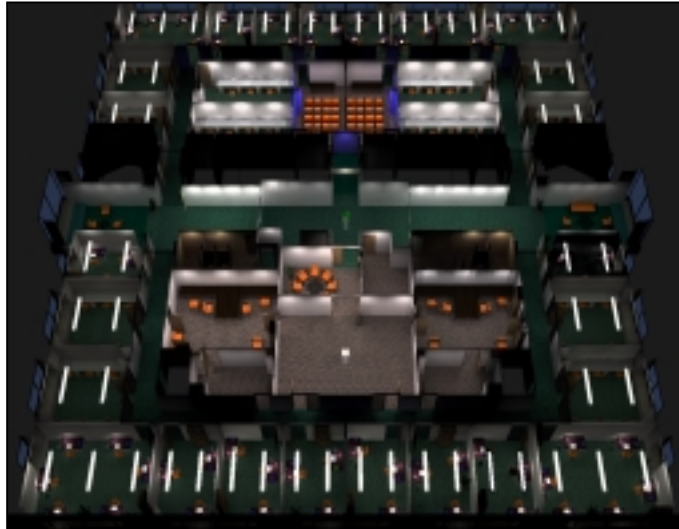
Adaptive Meshing



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Megaradiosity



From S. Teller, T. Funkhouser, C. Fowler, P. Hanrahan

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